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Amendments To The Specification

Replace the title of the invention with the following new title:

--DETECTION AND REMOVAL OF NOISE FROM AN IMAGE VIA MEDIAN FILTER AND MEAN-VARIANCE FILTER--

Please replace paragraph in the specification at page 4, lines 14 -18 with the following amended paragraph:

At this time, said α is the minimum threshold to detect a pixel containing impulsive noise and said χ_m is the mean of values of the pixels contained in the unit area. As above, threshold is dynamically calculated for each unit area. Thus, the noise removing system according to the present embodiment may detect impulsive noise more accurately.

Please replace the paragraphs in the specification ar page 5, between lines 17-31 with the following amended paragraphs:

The second filter 103 may employ the mean-variance filter like equation 3:

[Equation 3]

$$LND(i,j)=\frac{\sigma_k^2(i,j)k(i,j)+\bar{k}^2(i,j)}{\sigma_k^2(i,j)+\bar{k}(i,j)}$$

At this time, said σ_K *(i,j)* and $\bar{k}(i,j)$ indicate the variance and the mean of second pixels adjacent to *k(i, j)*, which is the coordinates of the first pixel, in the area formed of a predetermined size.

In the area of a predetermined size where there is no change, it is calculated as

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σ_k (i,j)=0. Accordingly, equation 3 may be represented as below:

[Equation 4]

$$LND(i,j) = \bar{k}(i,j)$$

Equation 4 indicates that a pixel value of the local neighborhood is approximate to the mean in the area and that Poisson noise has been effectively removed.

In contrast to this, in the area where image data contains edge or detailed information, the mean σ_k (i,j) takes on a higher value. Accordingly, equation 3 may be approximated as below: